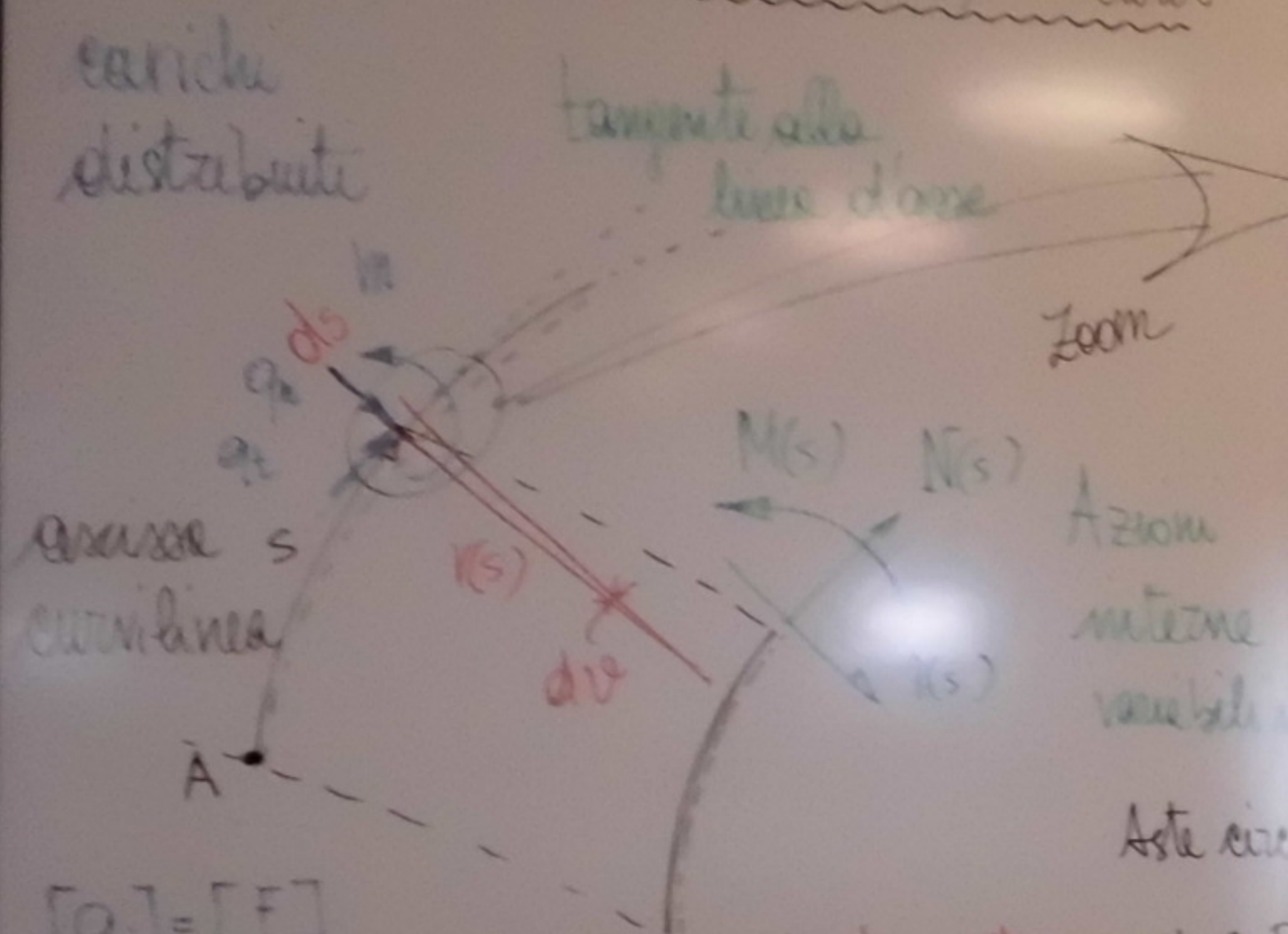


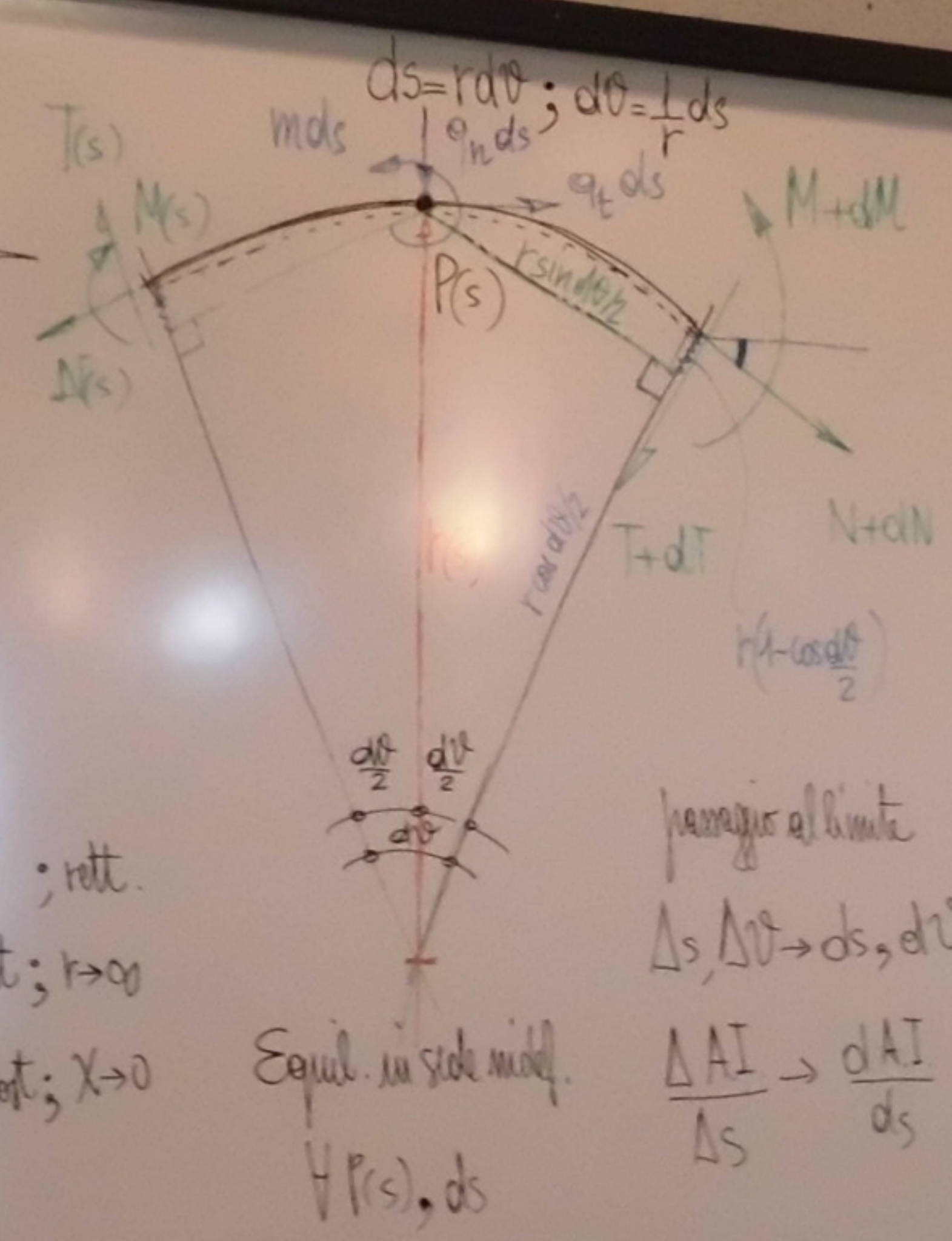
Eq indefinite di equilibrio delle aste curve



$[q_n] = [F]$
 $[m] = [F]$

$r = \rho(s) = \text{raggio di curvatura}$
 $\chi = \frac{1}{r} = \frac{1}{\rho}$ curvatura

Aste circolari; rett.
 $r = \rho = R = \text{cost}; r \rightarrow \infty$
 $\chi = \frac{1}{R} = \text{cost}; \chi \rightarrow 0$



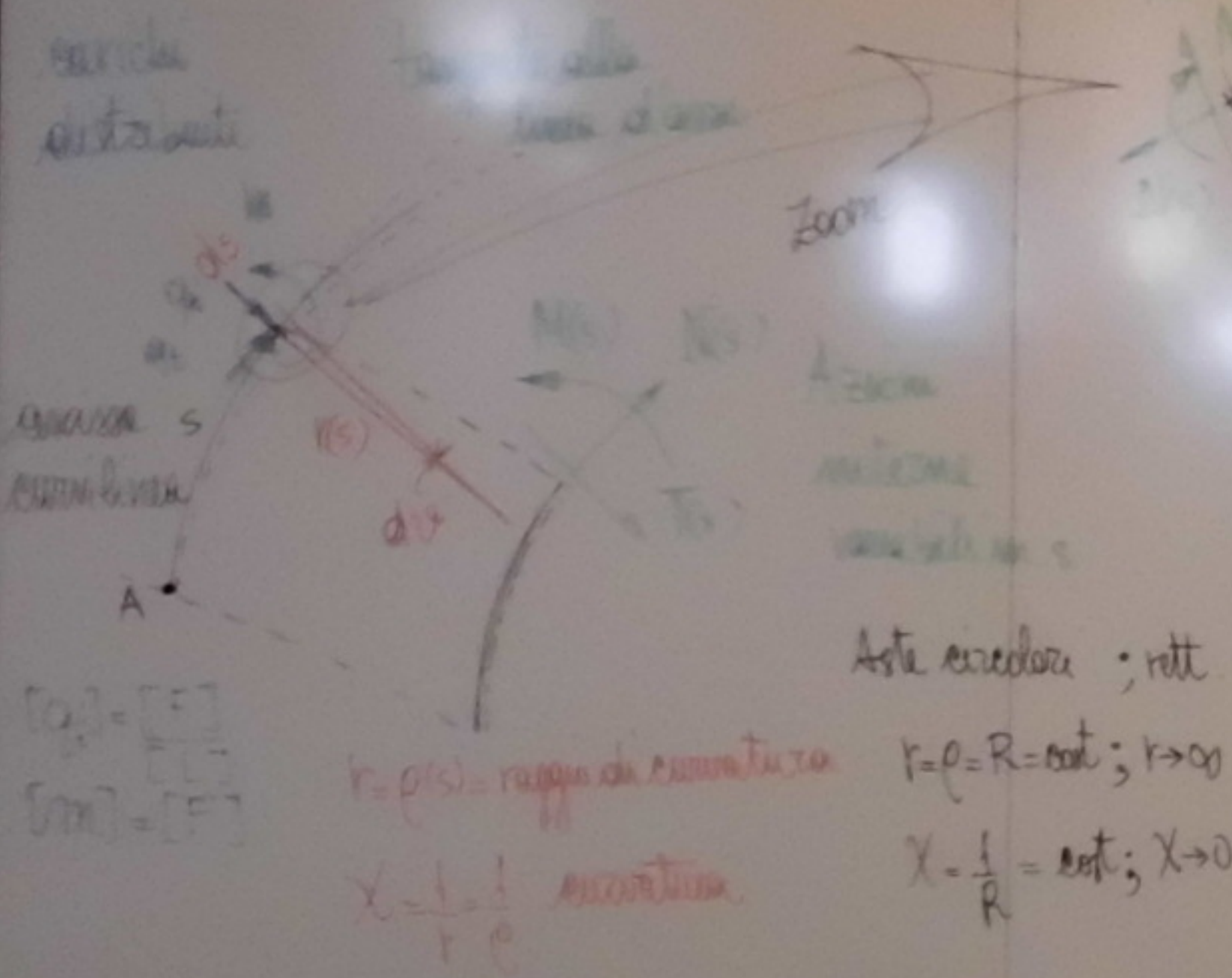
Equil. in sede inf. $\forall P(s), ds$

passaggio al limite
 $\Delta s, \Delta \theta \rightarrow ds, d\theta$
 $\frac{\Delta AI}{\Delta s} \rightarrow \frac{dAI}{ds}$

$\sum F_t^{ds} = 0 \Rightarrow (N + dN - N) \cos \frac{d\theta}{2} - 2T \sin \frac{d\theta}{2} + q_t ds = 0$
 $\sum F_n^{ds} = 0 \Rightarrow (T + dT - T) \sin \frac{d\theta}{2} + 2N \cos \frac{d\theta}{2} + q_n ds = 0$
 $\sum M_p^{ds} = 0 \Rightarrow M + dM - M + (N - N - dN) r \sin \frac{d\theta}{2} - (T + dT) r \cos \frac{d\theta}{2} + q_t ds r = 0$

$N'(s) = \frac{dN}{ds} = -q_t(s) + \frac{T(s)}{r(s)}$
 $T'(s) = \frac{dT}{ds} = -q_n(s) - \frac{N(s)}{r(s)}$
 $M'(s) = \frac{dM}{ds} = -m(s) + T(s)$

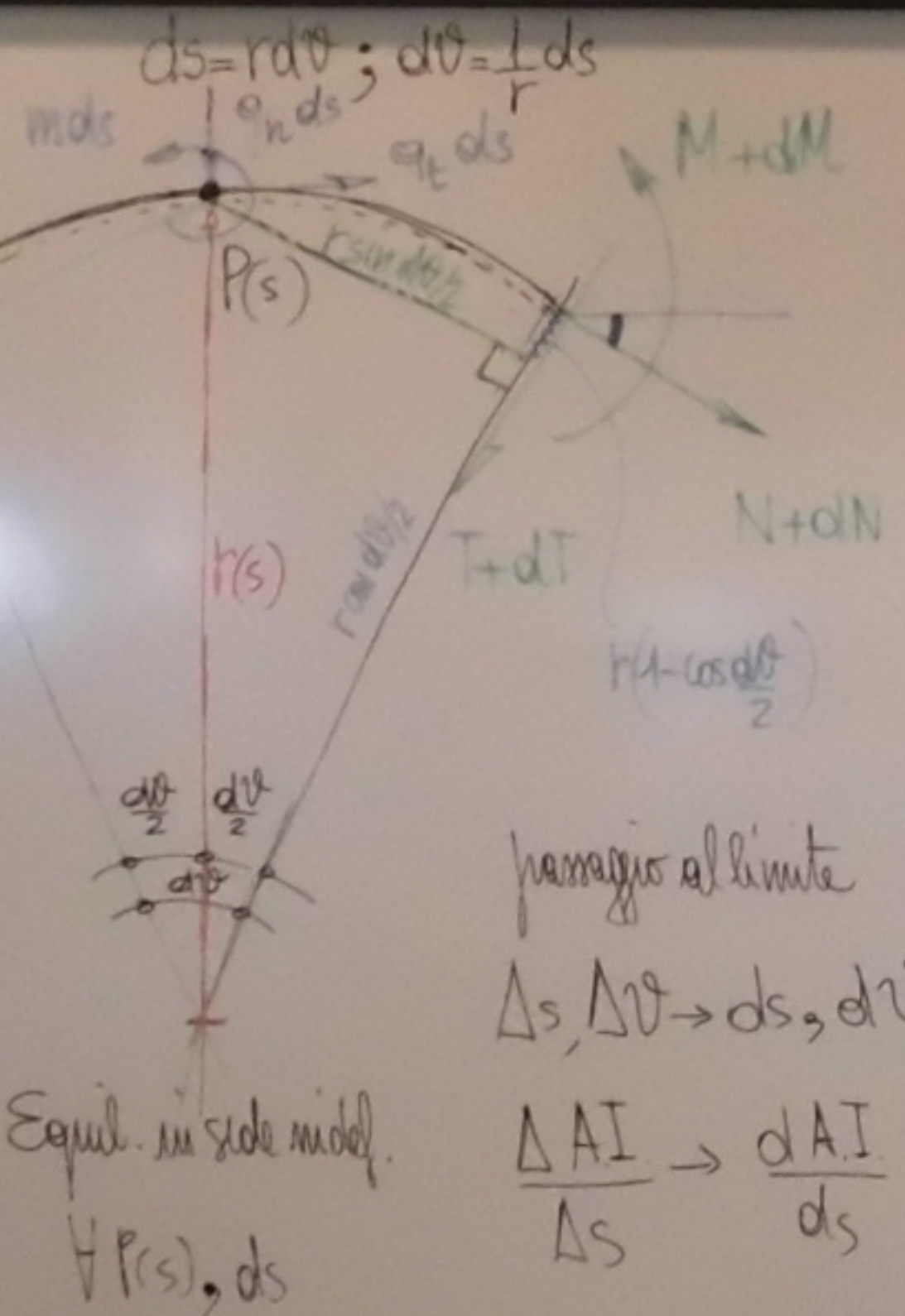
Eq indefinite di equilibrio delle aste curve



Aste circolari: rett

$r = \rho = R = \text{cost}$; $r \rightarrow \infty$

$\chi = \frac{1}{R} = \text{cost}$; $\chi \rightarrow 0$



passaggio al limite

$\Delta s, \Delta \theta \rightarrow ds, d\theta$

$\frac{\Delta AI}{\Delta s} \rightarrow \frac{dAI}{ds}$

Equil. in sede modif.
 $\forall P(s), ds$

$$\bullet \sum F_t^{ds} = 0 \Rightarrow (N + dN - N) \cos \frac{d\theta}{2} - 2T \sin \frac{d\theta}{2} - dT \sin \frac{d\theta}{2} + q_t ds = 0$$

$$N'(s) = \frac{dN}{ds} = -q_t(s) + \frac{T(s)}{r(s)}$$

accoppiamento T, N

$$\bullet \sum F_n^{ds} = 0 \Rightarrow (T + dT - T) \cos \frac{d\theta}{2} + 2N \sin \frac{d\theta}{2} + dN \sin \frac{d\theta}{2} + q_n ds = 0$$

$$T'(s) = \frac{dT}{ds} = -q_n(s) - \frac{N(s)}{r(s)}$$

accoppiamento T, N

$$\bullet \sum M_P^{ds} = 0 \Rightarrow M + dM - M + (N - N - dN) r (1 - \cos \frac{d\theta}{2}) - 2T r \sin \frac{d\theta}{2} - dT r \sin \frac{d\theta}{2} + m ds = 0$$

$$M'(s) = \frac{dM}{ds} = -m(s) + T(s)$$

come per aste rettilinee

$$N'(s) = -q_t(s) + \frac{T(s)}{r(s)} = -\frac{1}{r} \frac{dN}{ds}$$

Aste rettilinee ($r \rightarrow \infty$)

$$N'(s) = -q_t(s)$$

$$T'(s) = -q_n(s)$$

$$M'(s) = -m(s) + T(s)$$

Aste circolari ($r(s) = \text{cost } R$)

$$N'(s) = -q_t(s) + \frac{T(s)}{R} = \frac{1}{R} \frac{dN}{ds}$$

$$T'(s) = -q_n(s) - \frac{N(s)}{R} = -\frac{1}{R} \frac{dT}{ds}$$

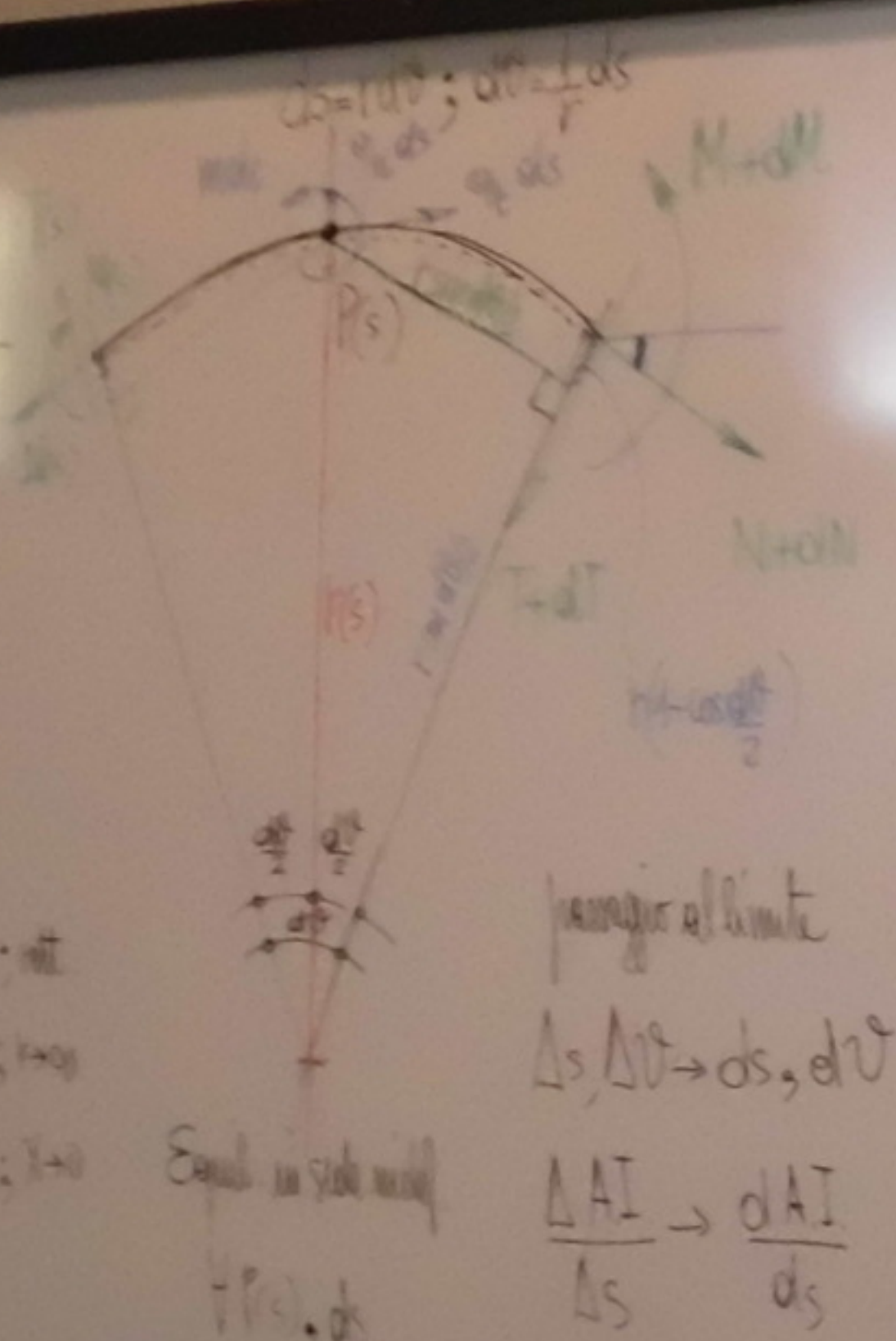
$$M'(s) = -m(s) + T(s) = \frac{1}{R} \frac{dM}{ds}$$

$$N'(0) = -q_t(0) + \frac{T(0)}{R}$$

$$T'(0) = -q_n(0) - \frac{N(0)}{R}$$

$$M'(0) = -m(0) + T(0)$$

In un arco di cerchio di raggio \$R\$ e angolo \$\theta\$, la risultante delle forze agenti sul segmento di arco è pari a quella agente sul segmento di corda.



$\bullet \Sigma F_t = 0 \Rightarrow (N + dN - N) \cos \frac{d\theta}{2} - 2T \sin \frac{d\theta}{2} - dT \frac{\sin d\theta}{2} + q_t ds = 0$
 $\sim 1 \quad \sim \frac{d\theta}{2} \quad \sim \frac{d\theta}{2} \quad \sim \frac{d\theta}{2}$
 $\sim 0 \quad \sim 0 \quad \sim 0$
 $\bullet \bullet \bullet$
 $N'(s) = \frac{dN}{ds} = -q_t(s) + \frac{T(s)}{r(s)}$
 accoppiamento \$N, T\$

$\bullet \Sigma F_n = 0 \Rightarrow (T + dT - T) \cos \frac{d\theta}{2} + 2N \sin \frac{d\theta}{2} - dN \frac{\sin d\theta}{2} + q_n ds = 0$
 $\sim 1 \quad \sim \frac{d\theta}{2} \quad \sim \frac{d\theta}{2} \quad \sim \frac{d\theta}{2}$
 $\sim 0 \quad \sim 0 \quad \sim 0$
 $\bullet \bullet \bullet$
 $T'(s) = \frac{dT}{ds} = -q_n(s) - \frac{N(s)}{r(s)}$
 accoppiamento \$T, N\$

$\bullet \Sigma M_p = 0 \Rightarrow M + dM - M + (N - N - dN) r (1 - \cos \frac{d\theta}{2}) - 2T r \sin \frac{d\theta}{2} - dT r \frac{\sin d\theta}{2} + m ds = 0$
 $\sim 1 \quad \sim \frac{d\theta}{2} \quad \sim \frac{d\theta}{2} \quad \sim \frac{d\theta}{2} \quad \sim \frac{d\theta}{2}$
 $\sim 0 \quad \sim 0 \quad \sim 0$
 $\bullet \bullet \bullet$
 $M'(s) = \frac{dM}{ds} = -m(s) + T(s)$
 accopp. \$M, T\$
 $M''(s) = \frac{d^2M}{ds^2} = -m'(s) + (-q_n - \frac{N}{r}) = -(m' + q_n) - \frac{N'}{r}$
 come per aste rettilinee

• Aste rettilinee (\$r \rightarrow \infty\$)

$$\begin{cases} N'(s) = -q_t(s) \\ T'(s) = -q_n(s) \\ M'(s) = -m(s) + T(s) \end{cases}$$

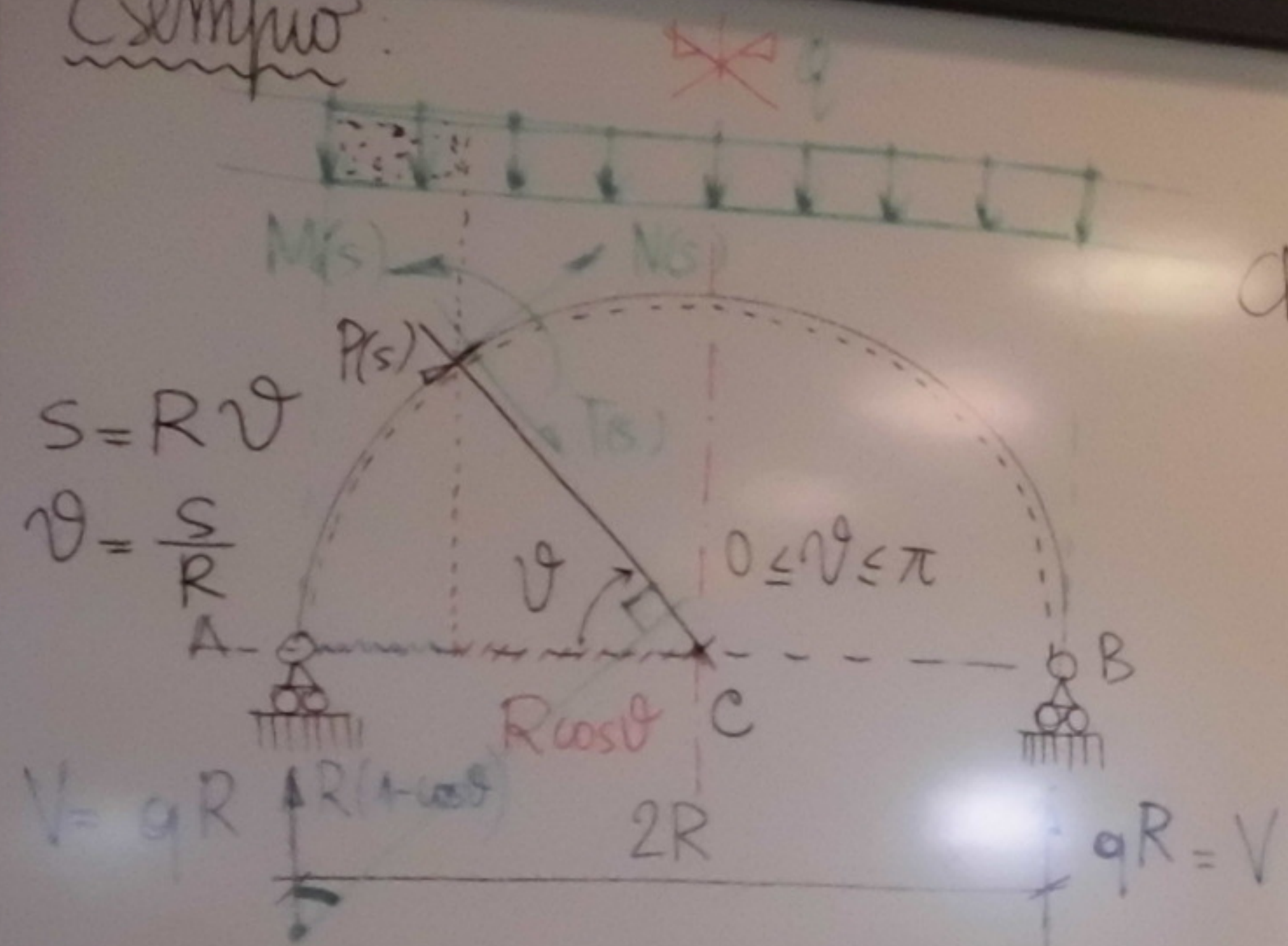
 $M''(s) = -(m' + q_n)$

• Aste circolari (\$r(s) = \text{cost. } R\$)

$$\begin{cases} N'(s) = -q_t(s) + \frac{T(s)}{R} = \frac{1}{R} \frac{dN}{ds} \\ T'(s) = -q_n(s) - \frac{N(s)}{R} = \frac{1}{R} \frac{dT}{ds} \\ M'(s) = -m(s) + T(s) = \frac{1}{R} \frac{dM}{ds} \end{cases}$$

$$\begin{cases} N'(0) = -q_t(0)R + T(0) \\ T'(0) = -q_n(0)R - N(0) \\ M'(0) = -m(0)R + RT(0) \end{cases}$$

Esempio:



Chiave $\vartheta = \pi/2$
sim.

antisim

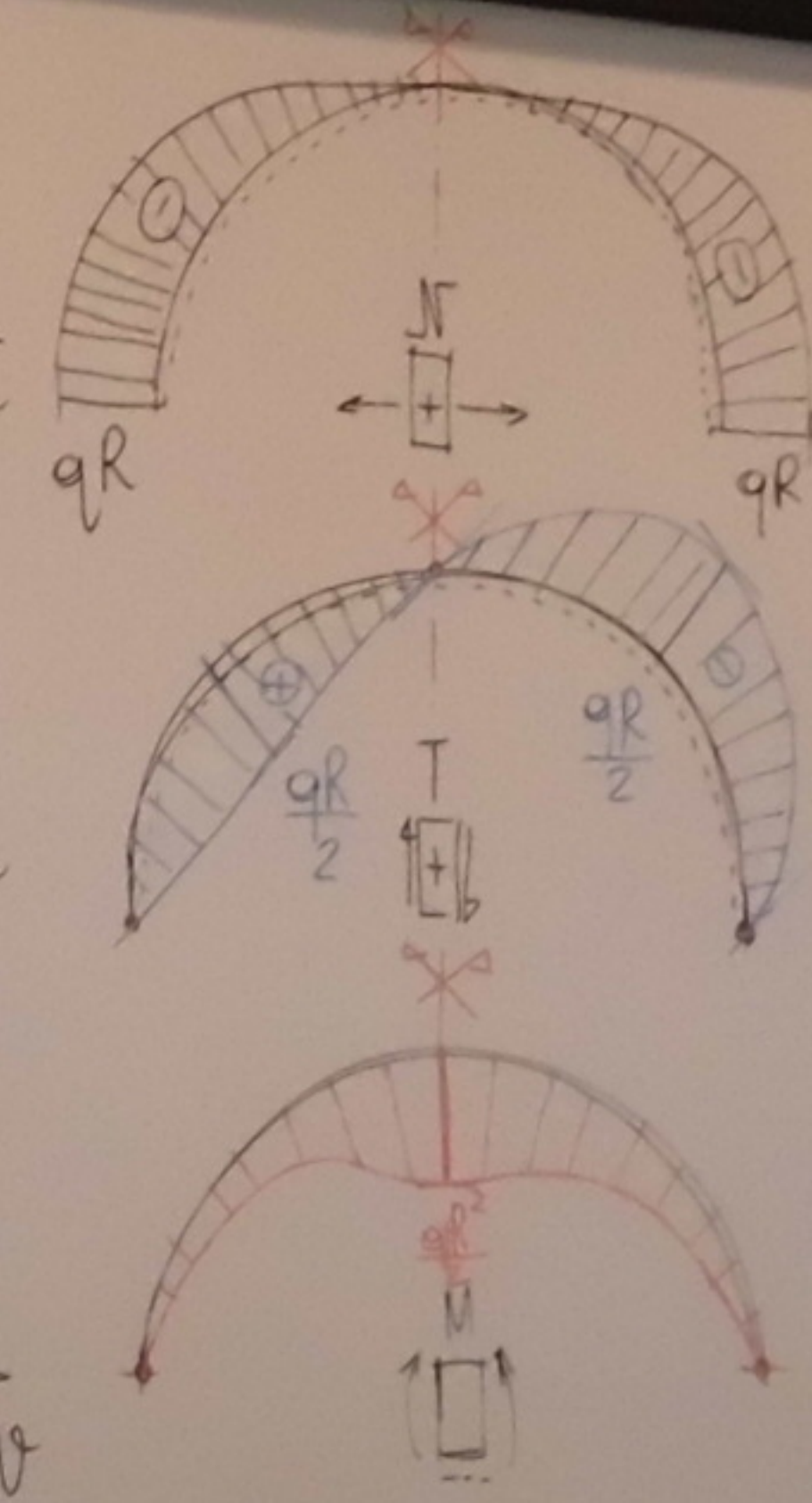
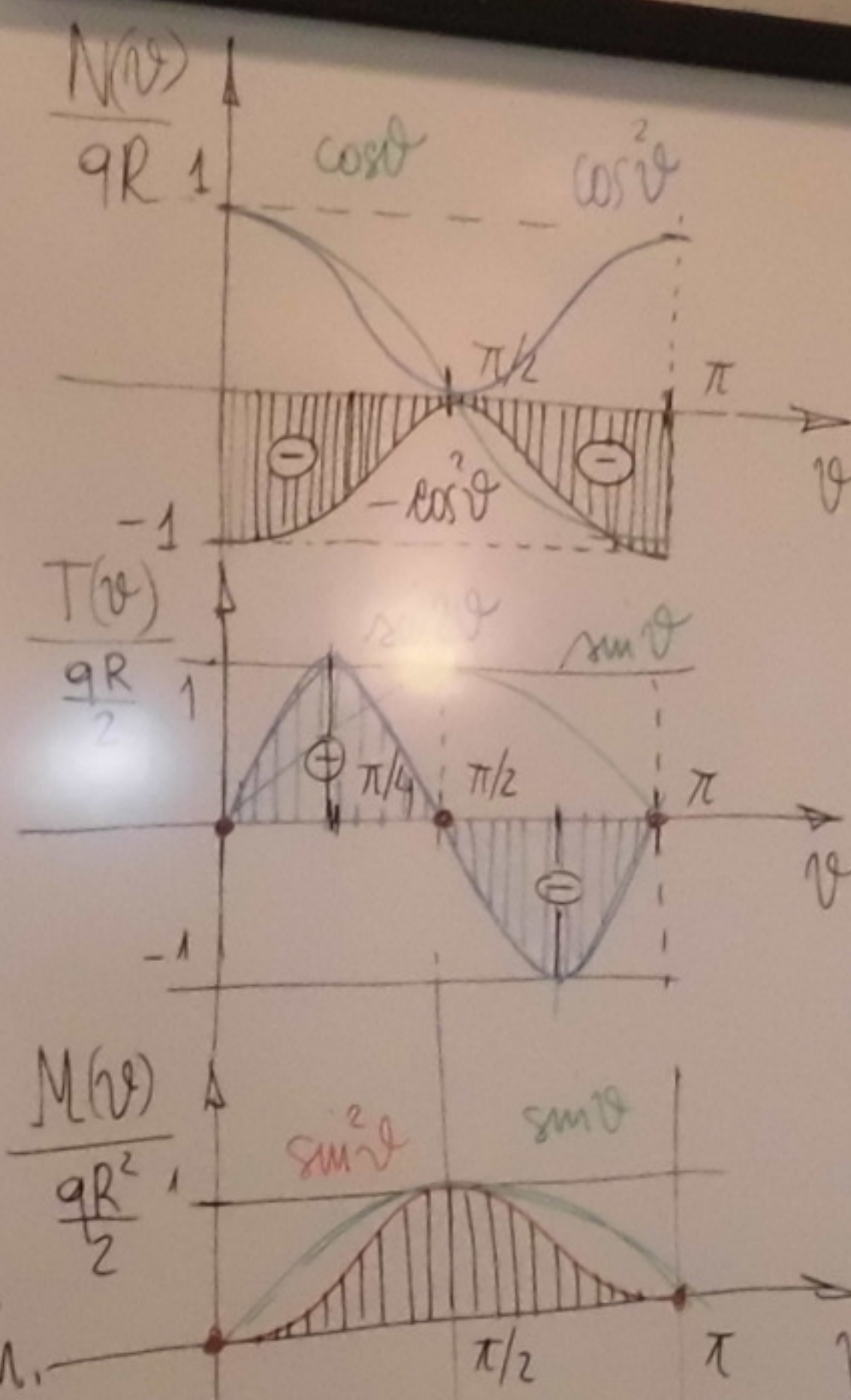
Azioni interne in $P(\vartheta)$

$$N(\vartheta) = (-qR + qR(1 - \cos\vartheta)) \cos\vartheta = -qR \cos^2\vartheta$$

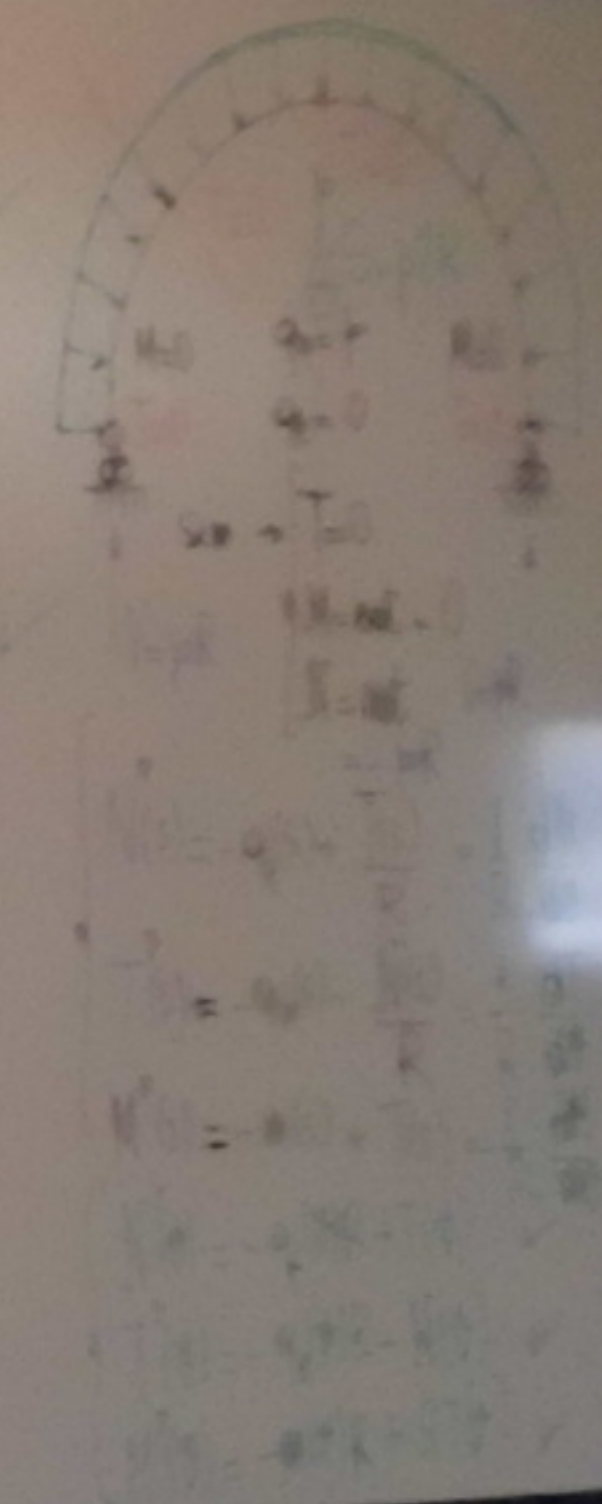
$$T(\vartheta) = (qR - qR(1 - \cos\vartheta)) \sin\vartheta = qR \sin\vartheta \cos\vartheta$$

$$M(\vartheta) = qR R(1 - \cos\vartheta) - qR(1 - \cos\vartheta)R(1 - \cos\vartheta) = qR^2(1 - \cos\vartheta) \left(1 - \frac{1 + \cos\vartheta}{2}\right) = \frac{qR^2}{2}(1 - \cos\vartheta)^2$$

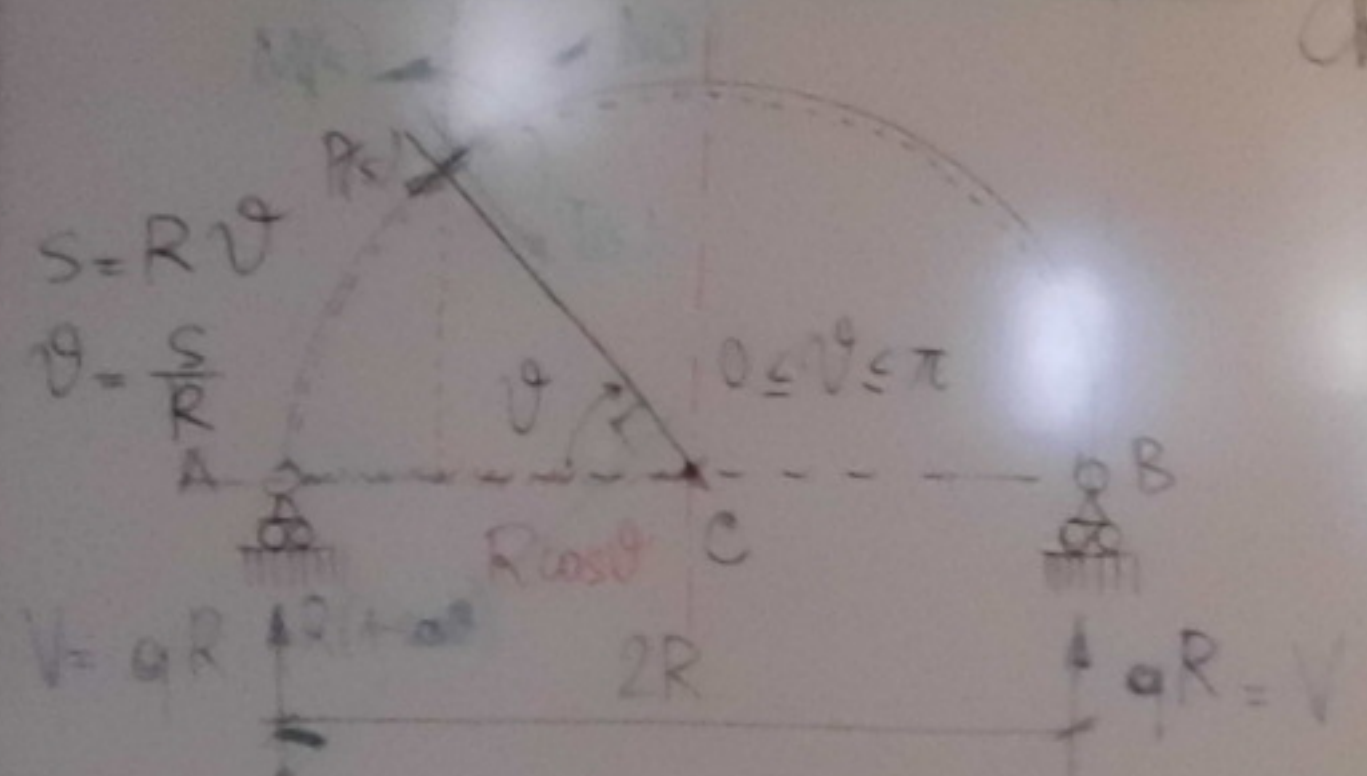
$$M(\vartheta) = \frac{qR^2}{2} 2 \sin^2\vartheta \cos\vartheta = \frac{qR^2}{2} \sin^2\vartheta = R T(\vartheta)$$



$N(\vartheta) = -qR \cos^2\vartheta$
 $T(\vartheta) = qR \sin\vartheta \cos\vartheta$
 $M(\vartheta) = \frac{qR^2}{2} \sin^2\vartheta$



Esempio



Chiuso $\theta = \pi/2$
sim

antisim

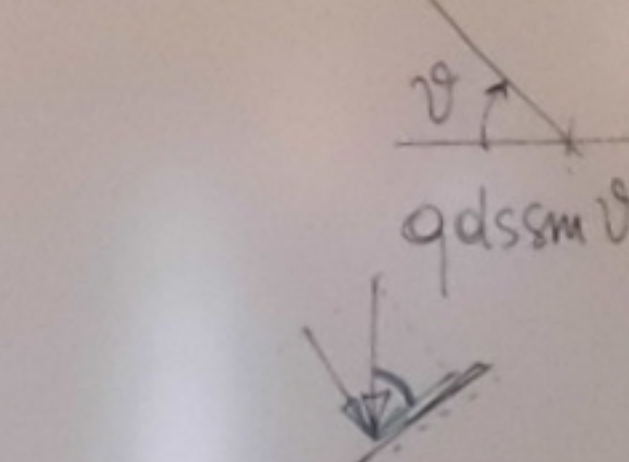
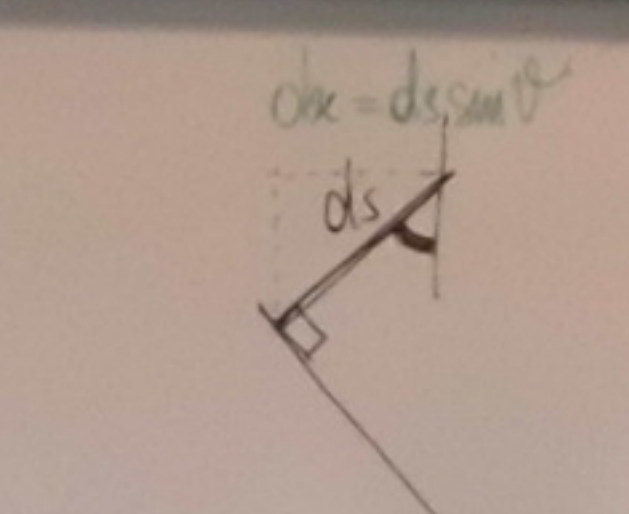
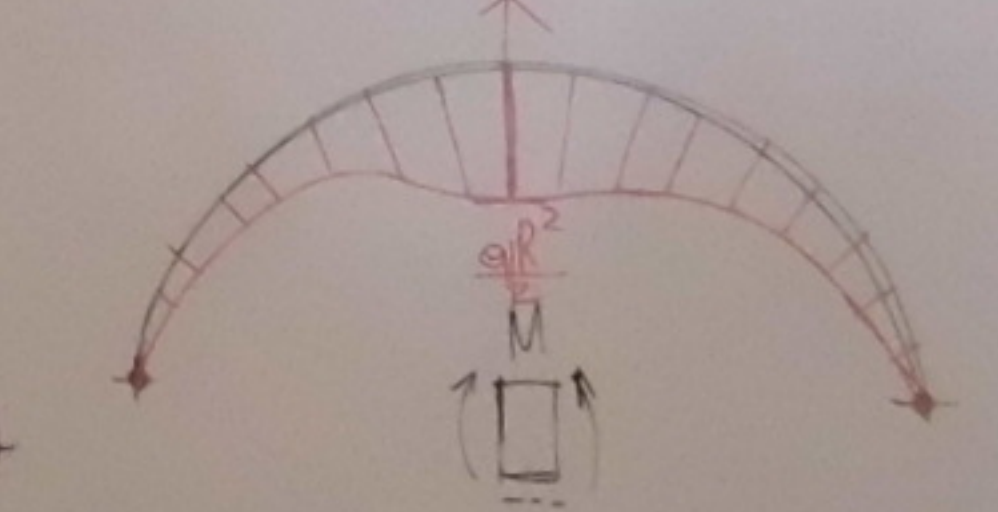
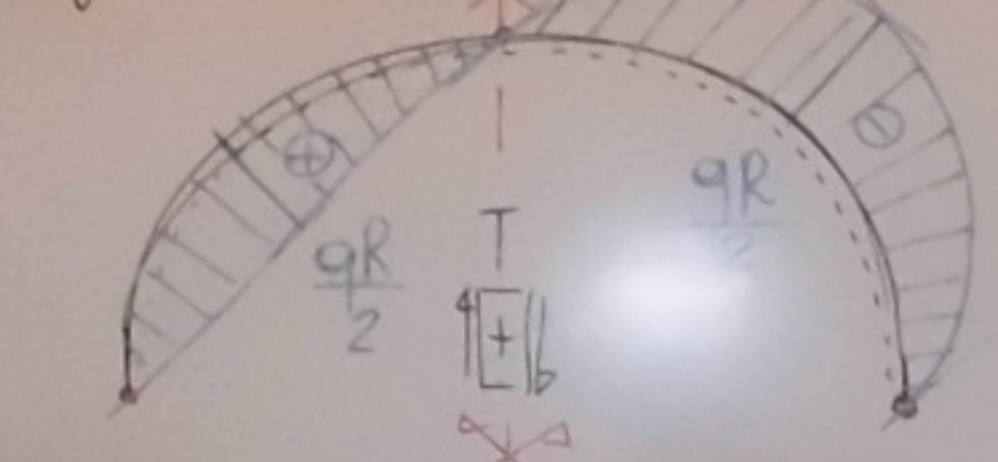
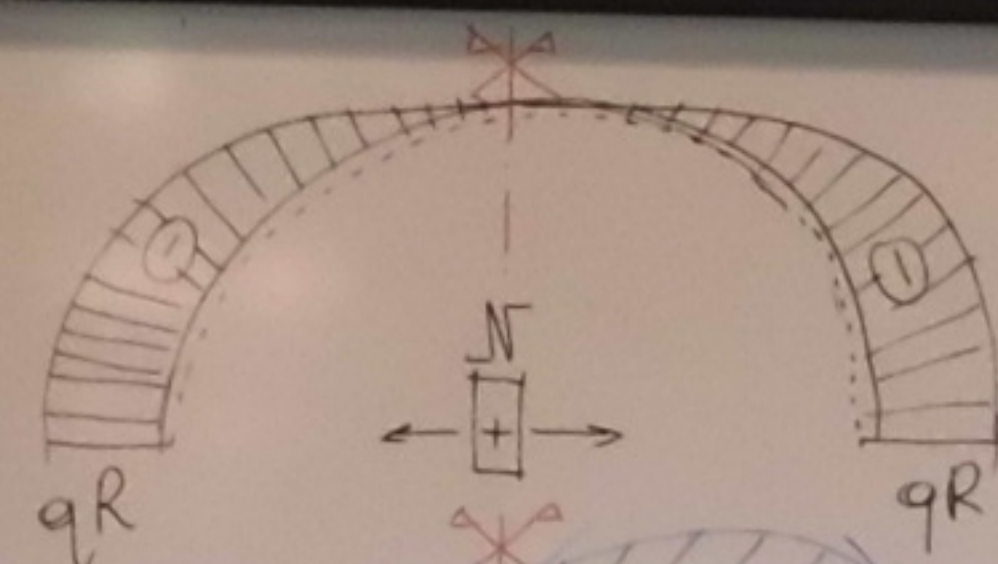
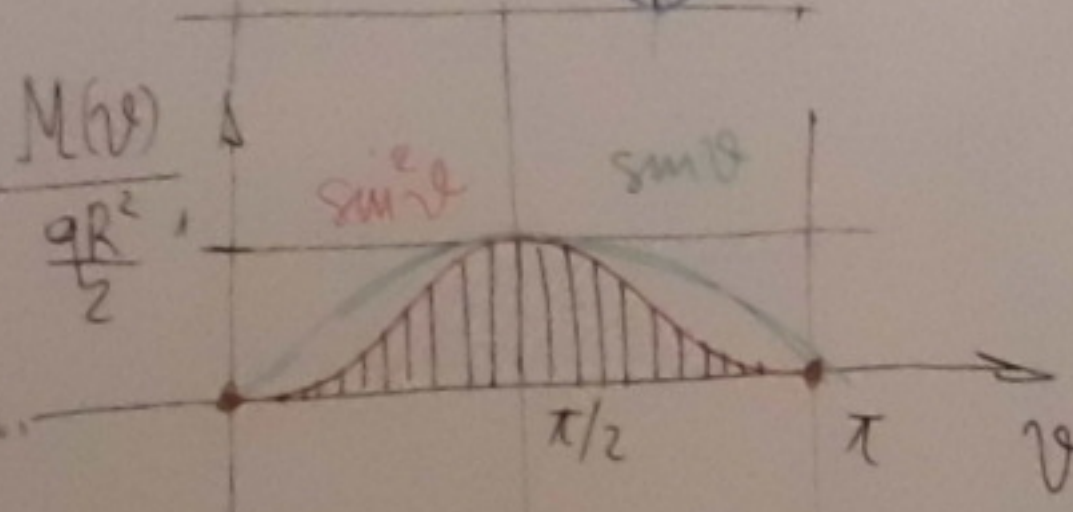
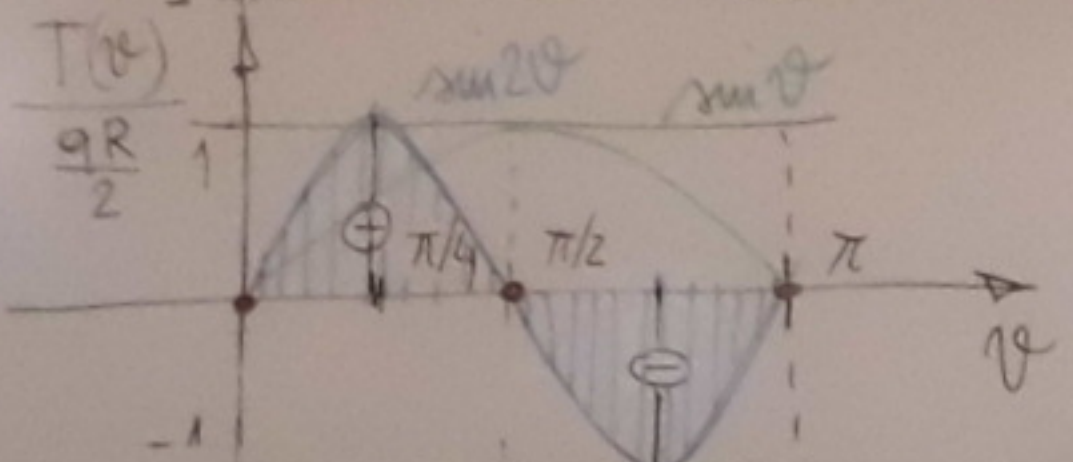
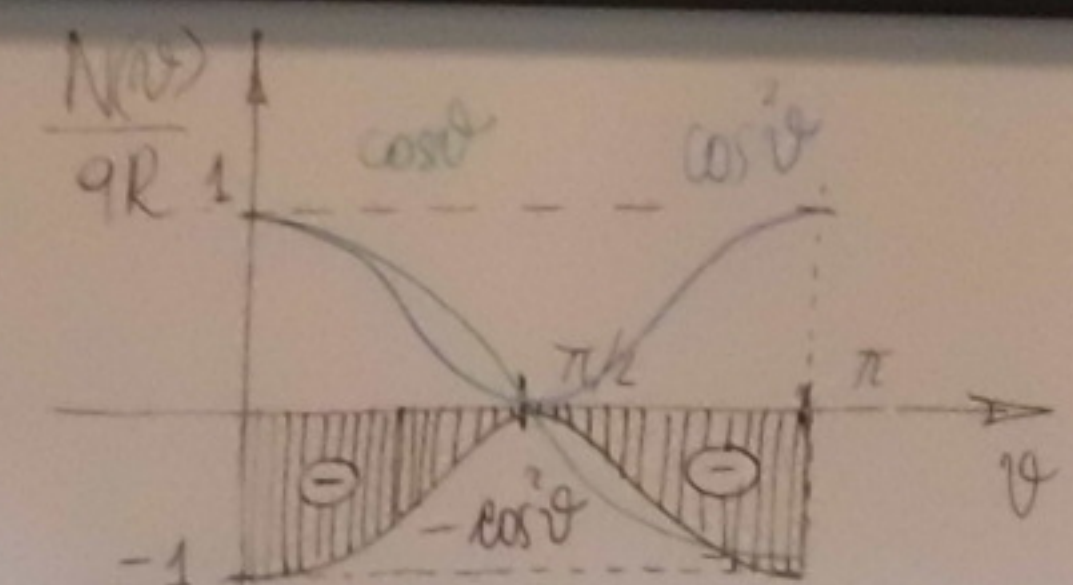
Azioni interne in P(θ)

$$N(\theta) = (-qR + qR(1 - \cos \theta)) \cos \theta = -qR \cos^2 \theta$$

$$T(\theta) = (qR - qR(1 - \cos \theta)) \sin \theta = qR \sin \theta \cos \theta$$

$$M(\theta) = qR R(1 - \cos \theta) - qR(1 - \cos \theta) R(1 - \cos \theta)$$

$$= qR^2(1 - \cos \theta) \left(\frac{1}{2} - \frac{1 + \cos \theta}{2} \right) = \frac{qR^2}{2}(1 - \cos^2 \theta) = \frac{qR^2}{2} \sin^2 \theta \rightarrow M'(\theta) = \frac{qR^2}{2} 2 \sin \theta \cos \theta = qR^2 \sin \theta \cos \theta = R T(\theta)$$



$$q_n = \frac{q ds \sin \theta \cos \theta}{ds} = q \sin \theta \cos \theta$$

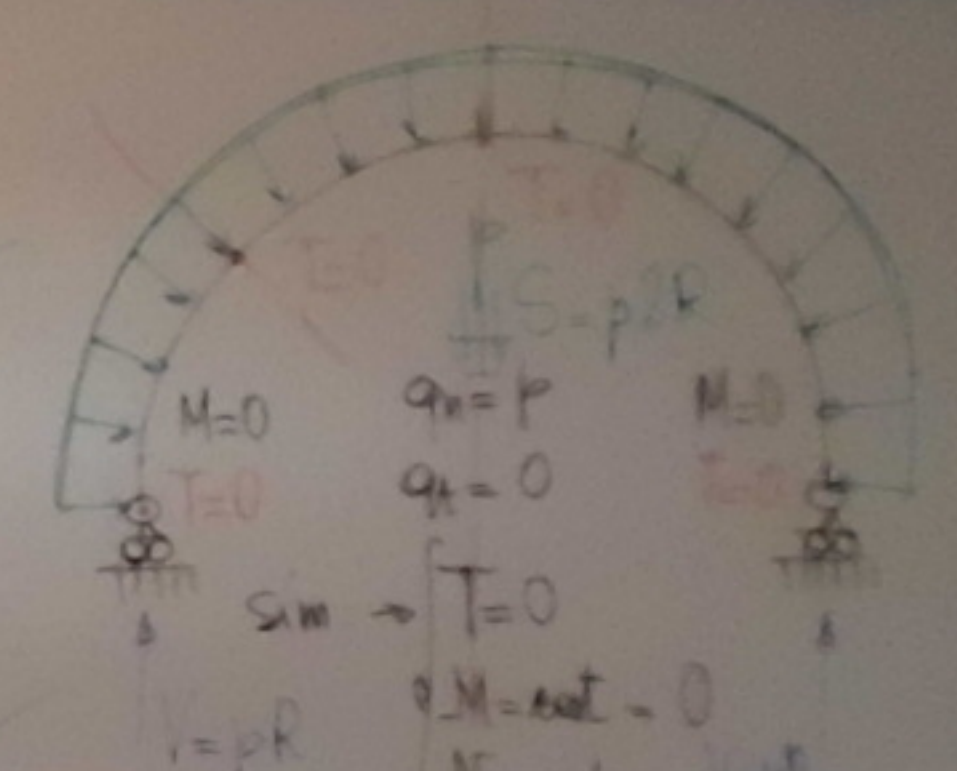
$$N'(\theta) = -qR 2 \cos \theta (-\sin \theta) = qR \sin 2\theta$$

$$= \frac{q}{2} \sin 2\theta R + \frac{qR}{2} \sin 2\theta$$

$$T'(\theta) = qR \cos 2\theta$$

$$= qR (\cos^2 \theta - \sin^2 \theta)$$

$$= -qR \sin^2 \theta + qR \cos^2 \theta$$



Equilibrium conditions at a point on the arch:

$$N'(\theta) = -q_n(s) + \frac{T(s)}{R} = -\frac{1}{R} \frac{dN}{d\theta}$$

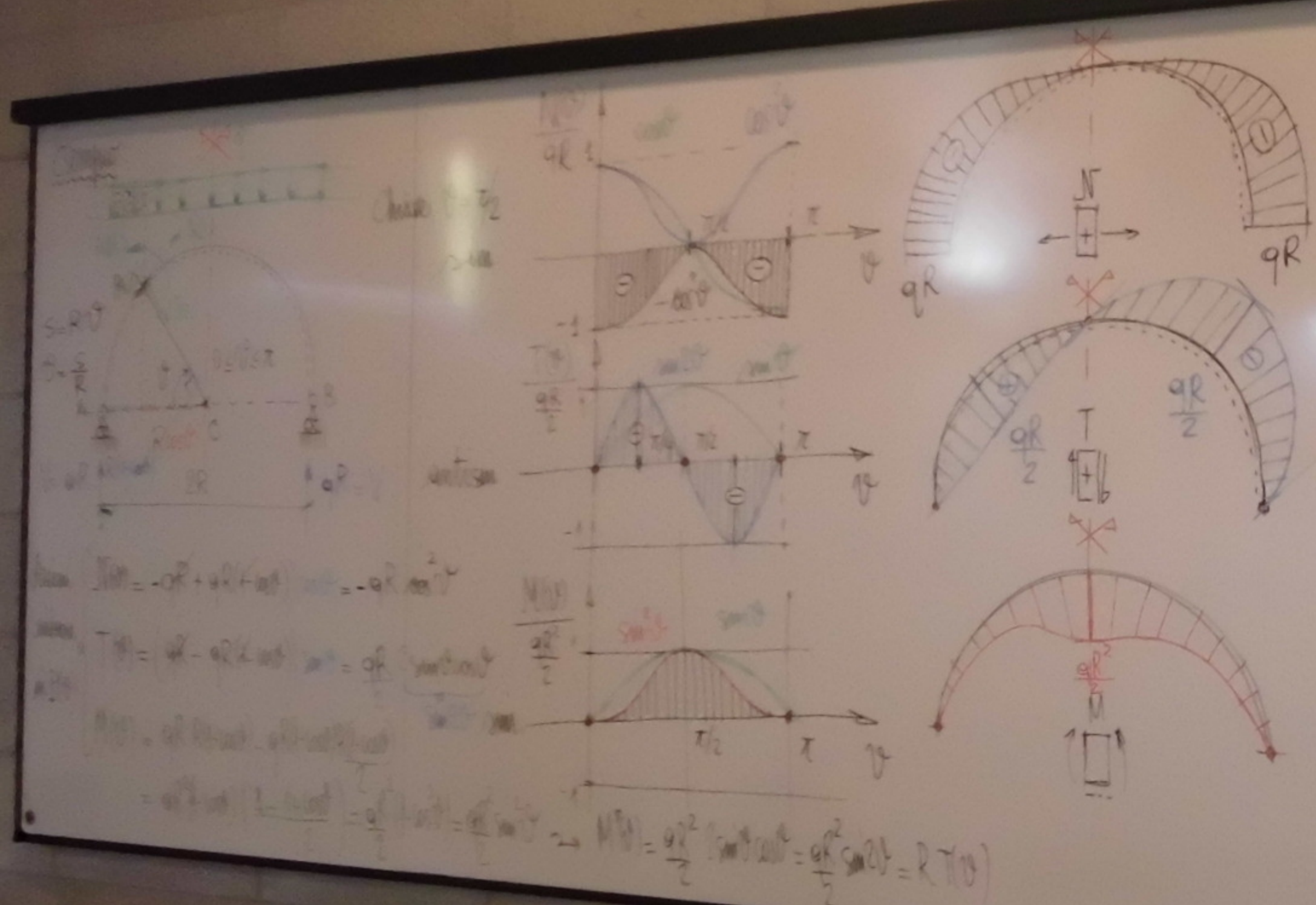
$$T'(\theta) = -q_n(s) - \frac{N(s)}{R} = -\frac{1}{R} \frac{dT}{d\theta}$$

$$M'(\theta) = -M(s) + T(s) = \frac{1}{R} \frac{dM}{d\theta}$$

$$N'(\theta) = -q_n + \frac{T}{R}$$

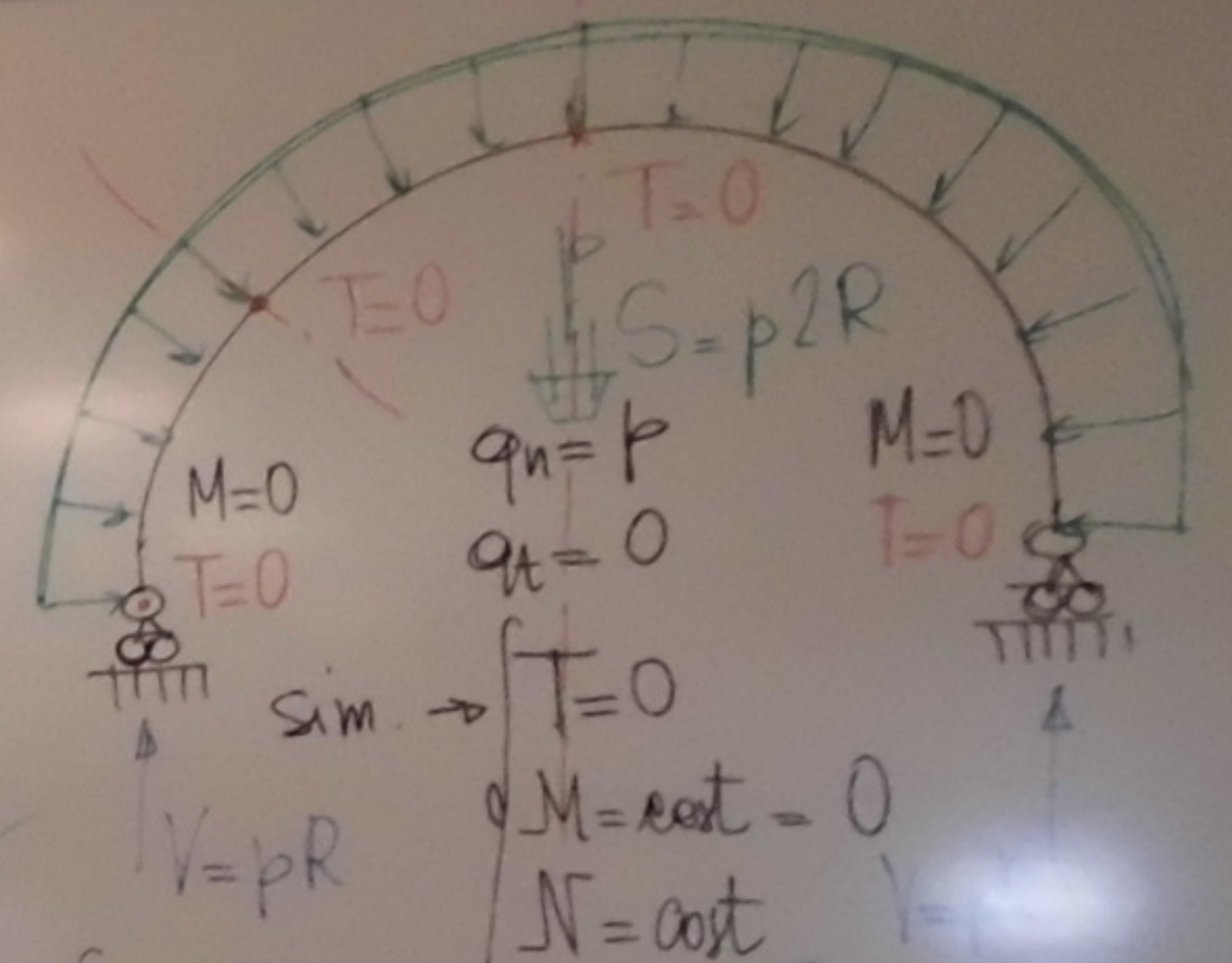
$$T'(\theta) = -q_n - \frac{N}{R}$$

$$M'(\theta) = -M + T$$



$q_n = \frac{q ds \sin^2 \vartheta}{ds}$
 $= q \sin^2 \vartheta$

$N'(\vartheta) = -qR \cos \vartheta (-\sin \vartheta)$
 $= qR \sin 2\vartheta$
 $T'(\vartheta) = \frac{qR}{2} \cos 2\vartheta$
 $= \frac{qR}{2} (\cos^2 \vartheta - \sin^2 \vartheta)$
 $= -\frac{qR}{2} \sin^2 \vartheta + \frac{qR}{2} \cos^2 \vartheta$



$N'(\vartheta) = -q_t(\vartheta) + \frac{T(\vartheta)}{R} = \frac{1}{R} \frac{dN}{d\vartheta}$
 $T'(\vartheta) = -q_n(\vartheta) - \frac{N(\vartheta)}{R} = \frac{1}{R} \frac{dT}{d\vartheta}$
 $M'(\vartheta) = -m(\vartheta) + T(\vartheta) = \frac{1}{R} \frac{dM}{d\vartheta}$
 $N'(\vartheta) = -q_t(\vartheta)R + T(\vartheta)$
 $T'(\vartheta) = -q_n(\vartheta)R - N(\vartheta)$
 $M'(\vartheta) = -m(\vartheta)R + RT(\vartheta)$