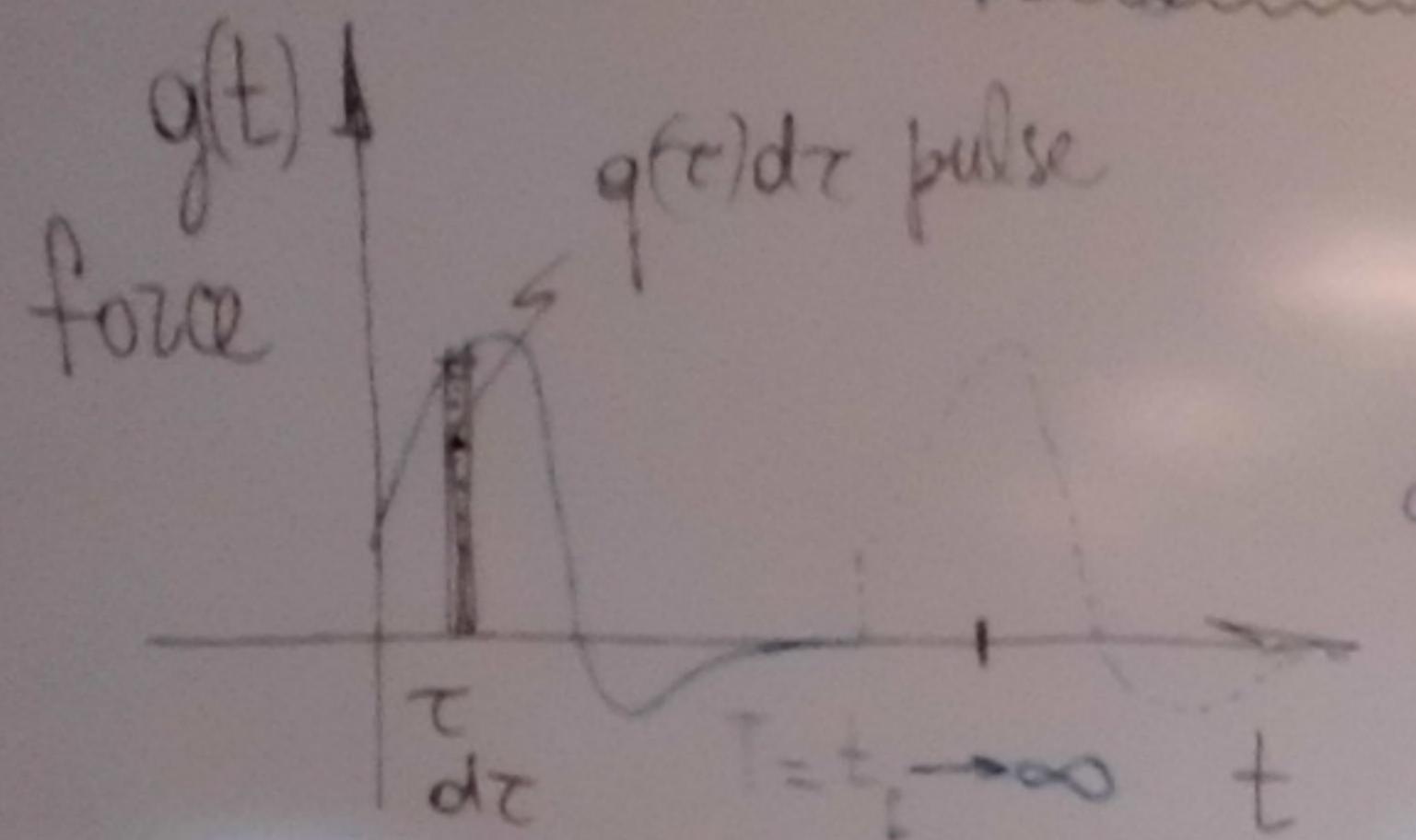


Response in the Frequency Domain



Property of Fourier transform:

$$F\left(\frac{d^n g(t)}{dt^n}\right) = (iw)^n F(g(t)) \quad \checkmark$$

$$\text{based on } \frac{d^n e^{iwt}}{dt^n} = (iw)^n e^{iwt}$$

$$\text{Let } iwt \rightarrow iw^2 \rightarrow (iw)^2 \rightarrow \dots \rightarrow \infty$$

$$\text{thus, } \frac{d^n g(t)}{dt^n} = \frac{1}{2\pi} \int_{-\infty}^{\infty} G(\omega) (iw)^n e^{iwt} d\omega$$

$$F\left(\frac{d^n g}{dt^n}\right) = (iw)^n F(g)$$

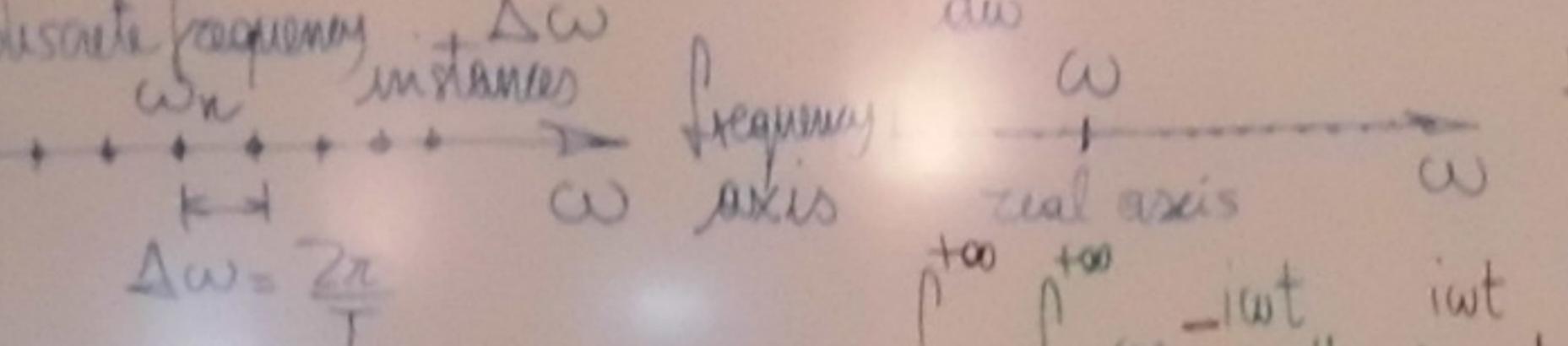
Proof

Fourier series:

$$g(t) = \sum_{n=-\infty}^{+\infty} C_n e^{i\omega_n t} \quad \omega_n = n\omega = n\frac{2\pi}{T} = n\Delta\omega$$

$$= \sum_{n=-\infty}^{+\infty} \frac{\Delta\omega}{2\pi} \int_{-T/2}^{T/2} g(t) e^{-i\omega_n t} dt e^{i\omega_n t}$$

$$= \sum_{n=-\infty}^{+\infty} \frac{\Delta\omega}{2\pi} \int_{-\infty}^{+\infty} g(t) e^{-i\omega_n t} dt e^{i\omega_n t} \quad T \rightarrow \infty \text{ (general non-periodic function)}$$



$$= \frac{1}{2\pi} \int_{-\infty}^{+\infty} \int_{-\infty}^{+\infty} g(t) e^{-i\omega t} dt e^{i\omega t} dw \quad \text{the frequency domain response}$$

Fourier transform: $G(\omega) = F(g(t))$

Inverse Fourier transform

$$g(t) = \frac{1}{2\pi} \int_{-\infty}^{+\infty} G(\omega) e^{i\omega t} dw$$

$$g(t) = F^{-1}(G(\omega))$$

Eq of motion:

$$F(m\ddot{u} + c\dot{u} + Ku = g(t))$$

$$[m(\omega)^2 + c\omega + K] U(\omega) = G(\omega)$$

$$H(\omega) = [K - m\omega^2 + c\omega] U(\omega) = G(\omega)$$

$$\frac{K - m\omega^2 + c\omega}{K m \omega^2}$$

$$\text{and represents the influence to harmonic loading}$$

$$U(\omega) = H(\omega) \cdot G(\omega)$$

$$\text{Frequency response function}$$

$$H(\omega) = \frac{1}{2} \frac{1}{\omega}$$

$$(A)$$

$$\int g(t) dt < \infty$$

$$\text{if } K + \frac{c}{m} + \frac{2\pi}{T}$$

$$H(\omega; \omega_0, \zeta)$$

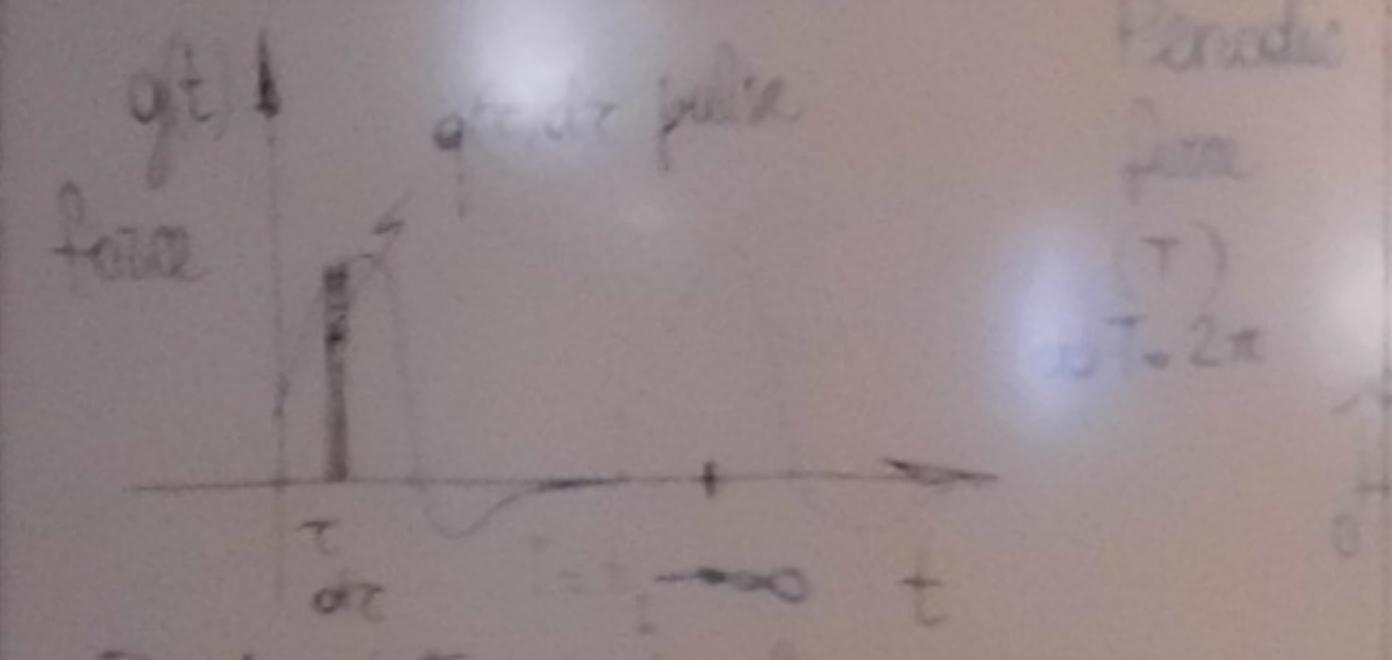
$$\text{is actually the Fourier transform of unit pulse response}$$

$$\text{Check: } F(1 \cdot \delta(\omega_0)) = \frac{1}{2\pi} \int_{-\infty}^{+\infty} 1 \cdot \delta(\omega_0) e^{i\omega t} dt = 1$$

$$\text{from 1}$$

$$\text{it's not true but the result is correct}$$

Response in the Frequency Domain



Property of Fourier transform

$$\begin{aligned} F\left(\frac{d^k g}{dt^k}\right) &= (\omega)^k F(g(t)) \quad \text{Proof:} \\ \text{and } \frac{d^k g}{dt^k} &= (\omega)^k \cdot i^{kt} \quad F\left(\frac{d^k g}{dt^k}\right) = (\omega)^k F(g) \\ \text{so } \int \frac{d^k g}{dt^k} dt &= (\omega)^k \int i^{kt} dt = (\omega)^k [i^{kt}] \Big|_{-\infty}^{+\infty} \\ \text{Then } \frac{d^k g}{dt^k} &= \lim_{\Delta t \rightarrow 0} \frac{g(t + \Delta t) - g(t)}{\Delta t}^k = G(\omega) \end{aligned}$$

Fourier series

$$g(t) = \sum_{n=-\infty}^{+\infty} C_n e^{j \omega_n t} = \sum_{n=-\infty}^{+\infty} \frac{A_n}{2\pi} \int_{-\infty}^{+\infty} g(t') e^{-j \omega_n t'} dt' \quad \text{int}$$

$\omega_n = n\omega = n\frac{2\pi}{T} = n\Delta\omega$
 $\Delta\omega = \frac{2\pi}{T}$

frequency axis: $\omega_0, \omega_1, \dots, \omega_n, \dots, \omega_{-1}, \omega_0, \dots, \omega_{-n}, \dots$

frequency axis: ω

$T \rightarrow \infty$ (general non-periodic function)

Eq of motion:

$$F(m\ddot{u} + c\dot{u} + Ku = g(t))$$

In fact, recall that response to harmonic force
 $F(m\ddot{u} + c\dot{u} + Ku = g(t))$
 $\ddot{u}(t) = \frac{1}{K + m\omega_0^2 + c\omega_0} g(t)$

$\omega_0 = \sqrt{\frac{k}{m}}$
 $\omega_r = \sqrt{\frac{k}{m+2c/m}} = \sqrt{\frac{m+2c}{m}}$

INPUT
 (force)
 $g(t)$

\rightarrow OUTPUT
 (response)
 $u(t)$

S	S
F	$H(\omega)$
D	$U(t)$

TIME DOMAIN $g(t)$ FREQUENCY DOMAIN $H(\omega)$

Condition in integral: $\int g(t)h(t-t)dt = u(t)$

Input \rightarrow Output
 $h \cdot g$ $u(t)$

$h(\omega)$

Fourier transform

$$g(t) = \frac{1}{2\pi} \int_{-\infty}^{+\infty} G(\omega) e^{j\omega t} d\omega$$

$$g(t) = F(G(\omega))$$

SC

$$\int_{-\infty}^{+\infty} |g(t)| dt < \infty$$

Dirichlet condition: $g(t) \in P_{\infty}$ $H(\omega) = \frac{1}{2\pi} \int_{-\infty}^{+\infty} g(t) e^{-j\omega t} dt$ (Δ)

$H(\omega) = \frac{1}{2\pi} \int_{-\infty}^{+\infty} g(t) e^{-j\omega t} dt$

is actually the Fourier transform of unit pulse response $h(t)$

Check: $F(2\pi \delta(\omega)) = \frac{1}{2\pi} \int_{-\infty}^{+\infty} 2\pi \delta(\omega) e^{-j\omega t} d\omega = 2\pi$ (from B)

it holds if $H(\omega) = H(0) = H_0$

$H(\omega) = H_0$

Response in the Frequency Domain

$$\begin{aligned}
 & q(t) = \sum_{n=-\infty}^{+\infty} C_n e^{i n \omega t} \quad (\text{Fourier Series}) \\
 & u(t) = \sum_{n=-\infty}^{+\infty} \frac{C_n}{j \omega} e^{i n \omega t} \quad (\text{Eq. of motion}) \\
 & \text{non periodic function} \\
 & \text{frequency axis } \omega \rightarrow \omega_0, \omega_1, \dots \\
 & \text{real axis } \omega \quad \omega \rightarrow \omega_0, \omega_1, \dots
 \end{aligned}$$

Property of Fourier Transform

$$F[\frac{d^2 g}{dt^2}] = (iw)^2 F[g]$$

$$\begin{aligned}
 & \text{Fourier transform} \\
 & G(w) = F(g(t)) \\
 & g(t) = \frac{1}{2\pi} \int_{-\infty}^{+\infty} G(w) e^{i w t} dw \\
 & f(t) = F^{-1}(G(w))
 \end{aligned}$$

Inverse Fourier transform

$$\begin{aligned}
 & \text{Eq. of motion: } F[m\ddot{u} + c\dot{u} + Ku = g(t)] \downarrow F(u(t)) \\
 & [m(iw)^2 + ciw + K] U(w) = G(w) \\
 & H(w) = [K - m w^2 + i c w]^{-1} U(w) = G(w) \\
 & \text{and represents the compliance to harmonic loading} \\
 & \text{Response in frequency domain: } U(w) = H(w) \cdot G(w)
 \end{aligned}$$

Check:

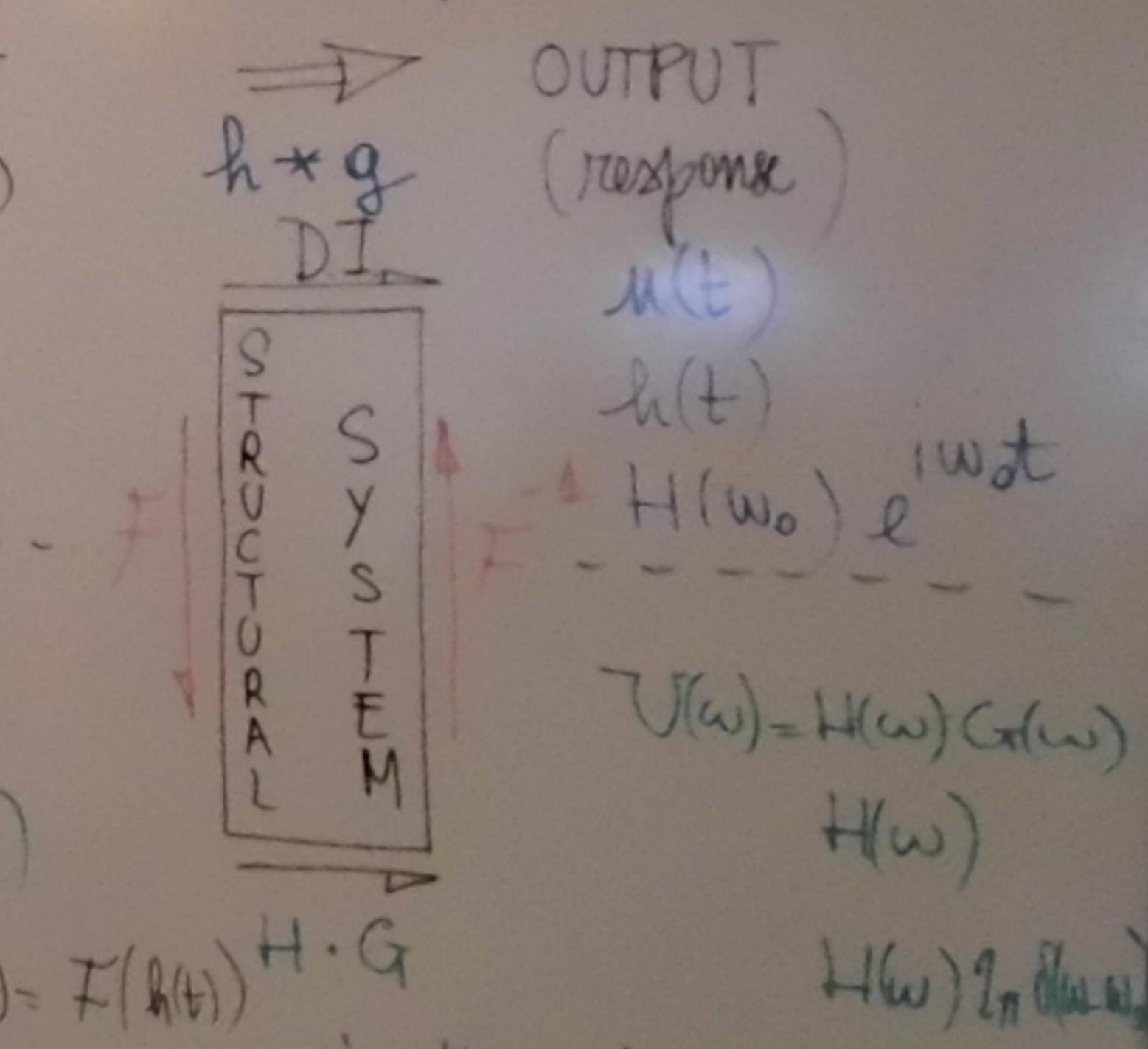
$$F(2\pi\delta(w-w_0)) = \frac{1}{2\pi} \int_{-\infty}^{+\infty} 2\pi \delta(w-w_0) e^{i w t} dw = e^{i w_0 t}$$

- In fact, recall that response to harmonic force: $\int g(t) h(t-t) dt = u(t)$

$$\begin{aligned}
 & \text{where } h(t) = \frac{1}{K} \frac{1}{1 - (\frac{\omega_0}{\omega})^2 + i \frac{2\pi w}{\omega}} e^{-i \omega t} = H(w_0) e^{-i \omega t}
 \end{aligned}$$

Convolution integral (Duhamel Integral)

$$\int g(t) h(t-t) dt = u(t)$$



FREQUENCY DOMAIN: $G(w)$

$$1$$

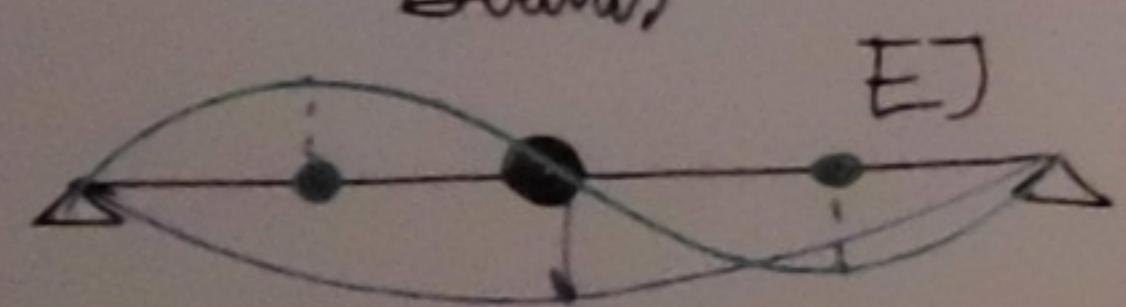
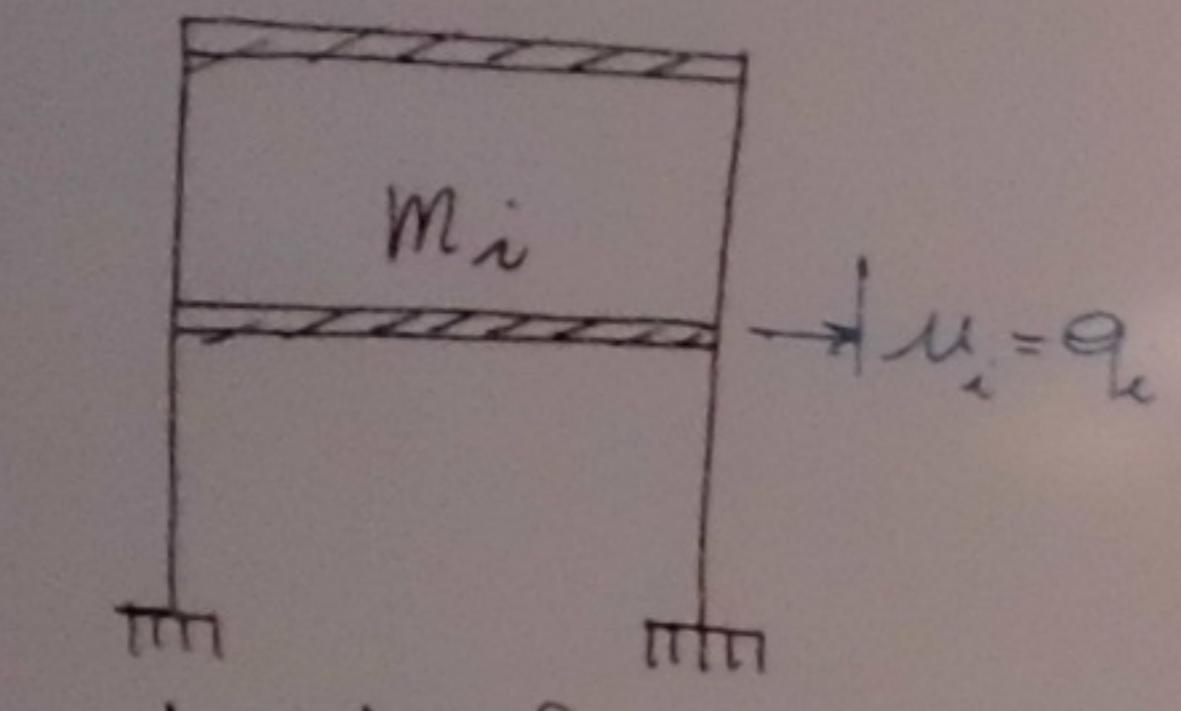
$$H(w)$$

$$2\pi \delta(w-w_0)$$

it could be proved that $H(w) = F(\delta(t))$

otherwise $\rightarrow = \text{gives } H(w) \text{ in } (\Delta)$

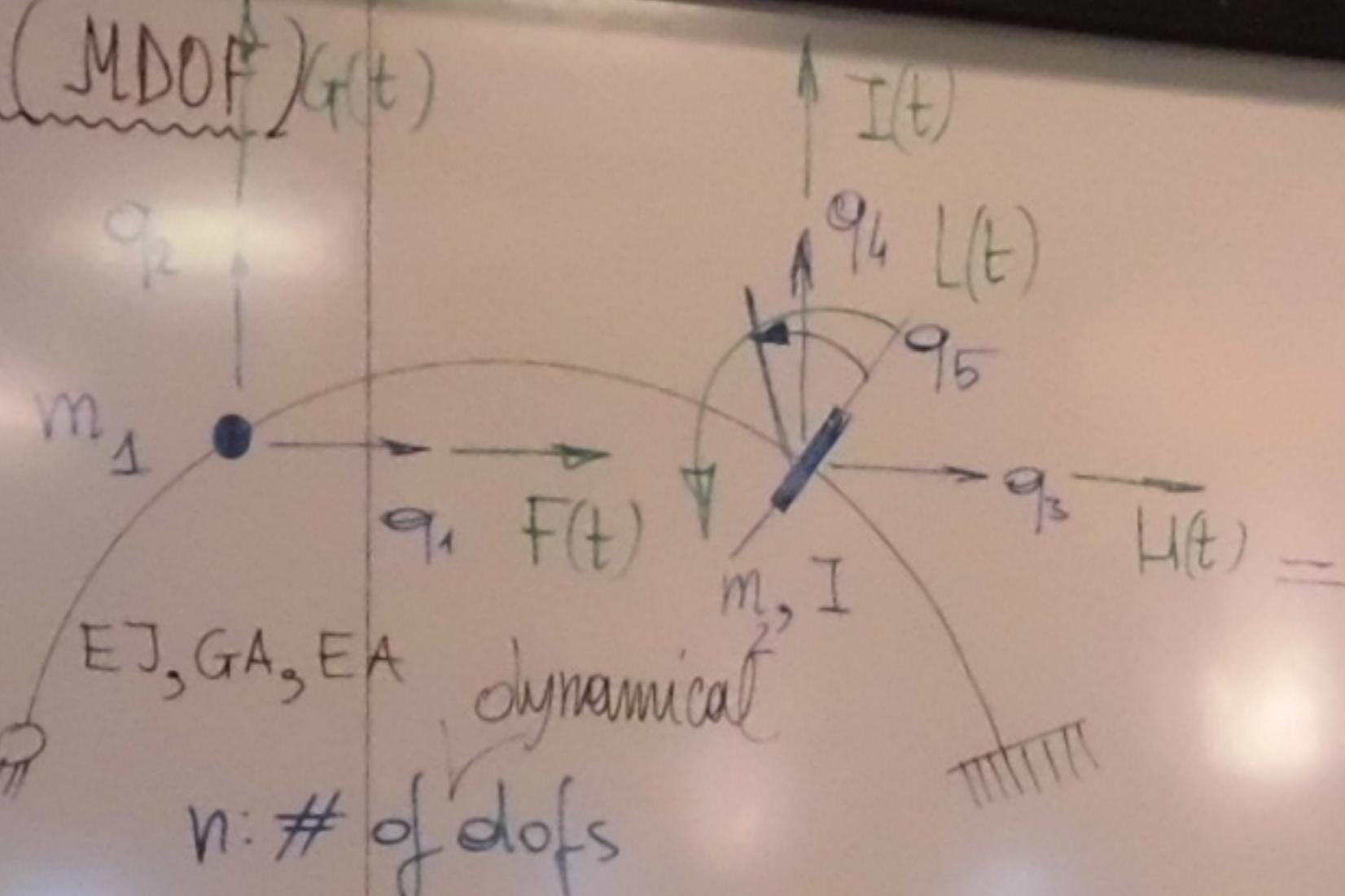
Multiple degree of freedom systems (MDOF) $\mathbf{q}(t)$



Continuous system \rightarrow discrete system

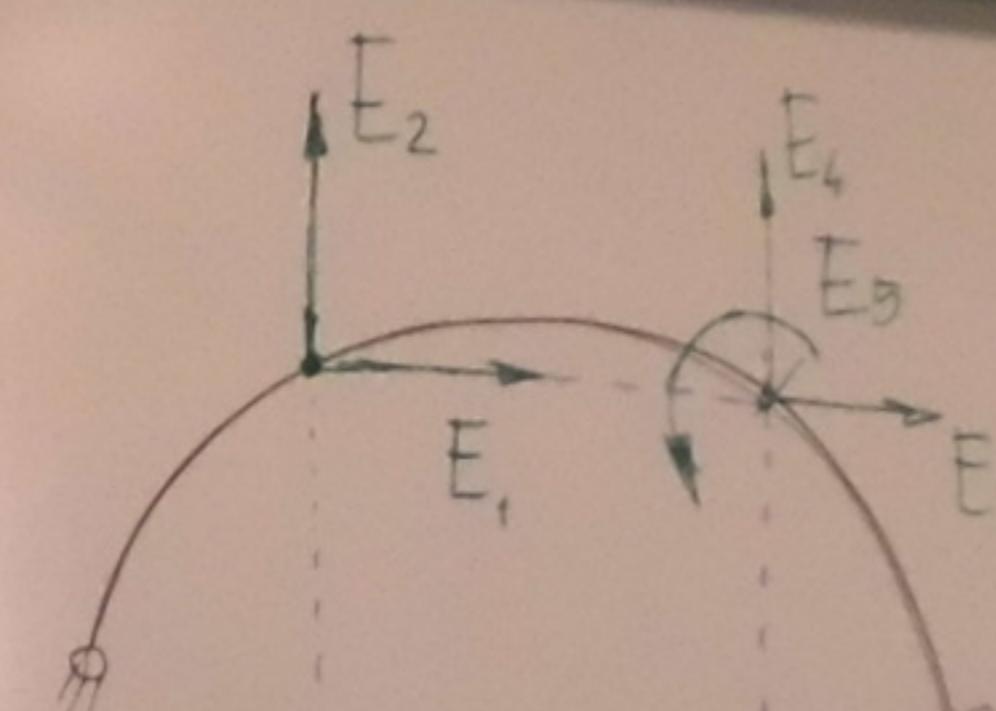
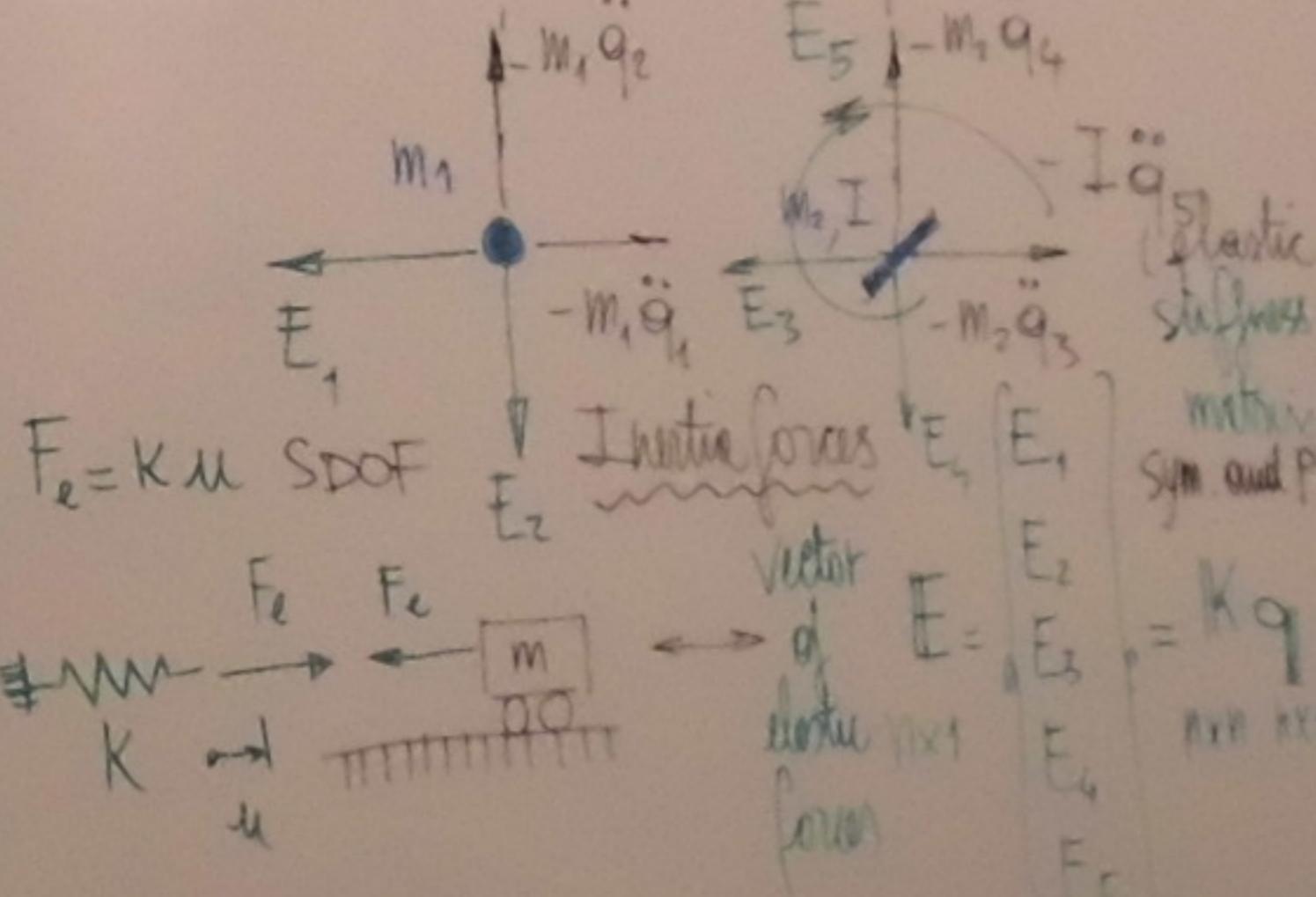
discretization (with lumped masses)

∞ dofs \rightarrow finite dofs



Vector of degrees of freedom
 $\mathbf{q} = \begin{bmatrix} q_1 \\ q_2 \\ q_3 \\ q_4 \\ q_5 \end{bmatrix}$ n x 1

Force vector (external loading actions)
 $\mathbf{F}_{ext} = \begin{bmatrix} F \\ G \\ H \\ I \\ L \end{bmatrix}$ n x 1



stiffness coefficients

$$K = K_{11} > K_{12}, K_{22}$$

(displacement method)

matrices

sym and PD

$K_{11} = K_{22}$

$K_{12} = K_{21}$

$$\mathbf{E} = \{E_1, E_2, \dots, E_n\}$$

$$= \{q^T k q + 1/2 E^T E\}$$

$$= 1/2 \times \alpha \times E^T E$$

Multiple degree of freedom systems (MDOF) (re)

